

NAG Fortran Library Routine Document

D05BYF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of *bold italicised* terms and other implementation-dependent details.

1 Purpose

D05BYF computes the fractional quadrature weights associated with the Backward Differentiation Formulae (BDF) of orders 4, 5 and 6. These weights can then be used in the solution of weakly singular equations of Abel type.

2 Specification

```
SUBROUTINE D05BYF(IORDER, IQ, LENFW, WT, SW, LDSW, WORK, LWK, IFAIL)
INTEGER          IORDER, IQ, LENFW, LDSW, LWK, IFAIL
real           WT(LenFW), SW(LDSW, 2*IORDER-1), WORK(LWK)
```

3 Description

D05BYF computes the weights $W_{n,j}$ and ω_i for a family of quadrature rules related to a BDF method for approximating the integral:

$$\frac{1}{\sqrt{\pi}} \int_0^t \frac{\phi(s)}{\sqrt{t-s}} ds \simeq \sqrt{h} \sum_{j=0}^{2p-2} W_{n,j} \phi(jh) + \sqrt{h} \sum_{j=2p-1}^n \omega_{n-j} \phi(jh), \quad 0 \leq t \leq T, \quad (1)$$

with $t = nh$ ($n \geq 0$), for some given h . In (1), p is the order of the BDF method used and $W_{n,j}$, ω_i are the fractional starting and the fractional convolution weights respectively. The algorithm for the generation of ω_i is based on Newton's iteration. Fast Fourier transform (FFT) techniques are used for computing these weights and subsequently $W_{n,j}$ (see Baker and Derakhshan (1987) and Henrici (1979) for practical details and Lubich (1986) for theoretical details). Some special functions can be represented as the fractional integrals of simpler functions and fractional quadratures can be employed for their computation (see Lubich (1986)). A description of how these weights can be used in the solution of weakly singular equations of Abel type is given in Section 8.

4 References

Baker C T H and Derakhshan M S (1987) Computational approximations to some power series *Approximation Theory* (ed L Collatz, G Meinardus and G Nürnberger) **81** 11–20

Henrici P (1979) Fast Fourier methods in computational complex analysis *SIAM Rev.* **21** 481–529

Lubich Ch (1986) Discretized fractional calculus *SIAM J. Math. Anal.* **17** 704–719

5 Parameters

1: IORDER – INTEGER *Input*

On entry: the order of the BDF method to be used, p .

Constraint: $4 \leq \text{IORDER} \leq 6$.

2: IQ – INTEGER *Input*

On entry: determines the number of weights to be computed. By setting IQ to a value, $2^{\text{IQ}+1}$ fractional convolution weights are computed.

Constraint: $\text{IQ} \geq 0$.

- 3: LENFW – INTEGER *Input*
On entry: the length of the array WT.
Constraint: $\text{LENFW} \geq 2^{\text{IQ}+2}$.
- 4: WT(LenFW) – *real* array *Output*
On exit: the first $2^{\text{IQ}+1}$ elements of WT contains the fractional convolution weights ω_i , for $i = 0, 1, \dots, 2^{\text{IQ}+1} - 1$. The remainder of the array is used as workspace.
- 5: SW(LDSW, 2*IORDER-1) – *real* array *Output*
On exit: $\text{SW}(n, j+1)$ contains the fractional starting weights $W_{n-1, j}$, for $n = 1, 2, \dots, (2^{\text{IQ}+1} + 2 \times \text{IORORDER} - 1)$; $j = 0, 1, \dots, 2 \times \text{IORORDER} - 2$.
- 6: LDSW – INTEGER *Input*
On entry: the first dimension of the array SW as declared in the (sub)program from which D05BYF is called.
Constraint: $\text{LDSW} \geq 2^{\text{IQ}+1} + 2 \times \text{IORORDER} - 1$.
- 7: WORK(LWK) – *real* array *Workspace*
8: LWK – INTEGER *Input*
On entry: the dimension of the array WORK as declared in the (sub)program from which D05BYF is called.
Constraint: $\text{LWK} \geq 2^{\text{IQ}+3}$.
- 9: IFAIL – INTEGER *Input/Output*
On entry: IFAIL must be set to 0, -1 or 1. Users who are unfamiliar with this parameter should refer to Chapter P01 for details.
On exit: $\text{IFAIL} = 0$ unless the routine detects an error (see Section 6).
For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, for users not familiar with this parameter the recommended value is 0. **When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.**

6 Error Indicators and Warnings

If on entry $\text{IFAIL} = 0$ or -1 , explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

$\text{IFAIL} = 1$

- On entry, $\text{IORORDER} < 4$ or $\text{IORORDER} > 6$,
- or $\text{IQ} < 0$,
- or $\text{LENFW} < 2^{\text{IQ}+2}$,
- or $\text{LDSW} < 2^{\text{IQ}+1} + 2 \times \text{IORORDER} - 1$,
- or $\text{LWK} < 2^{\text{IQ}+3}$.

7 Accuracy

None.

8 Further Comments

Fractional quadrature weights can be used for solving weakly singular integral equations of Abel type. In this section, we propose the following algorithm which users may find useful in solving a linear weakly singular integral equation of the form

$$y(t) = f(t) + \frac{1}{\sqrt{\pi}} \int_0^t \frac{K(t,s)y(s)}{\sqrt{t-s}} ds, \quad 0 \leq t \leq T, \quad (2)$$

using D05BYF. In (2), $K(t,s)$ and $f(t)$ are given and the solution $y(t)$ is sought on a uniform mesh of size h such that $T = Nh$. Discretization of (2) yields

$$y_n = f(nh) + \sqrt{h} \sum_{j=0}^{2p-2} W_{n,j} K(nh, jh) y_j + \sqrt{h} \sum_{j=2p-1}^n \omega_{n-j} K(nh, jh) y_j, \quad (3)$$

where $y_n \simeq y(nh)$. We propose the following algorithm for computing y_n from (3) after a call to D05BYF:

- (a) Set $N = 2^{IQ+1} + 2 \times \text{IORDER} - 2$ and $h = T/N$.
 (b) Equation (3) requires $2 \times \text{IORDER} - 2$ starting values, y_j , for $j = 1, 2, \dots, 2 \times \text{IORDER} - 2$, with $y_0 = f(0)$. These starting values can be computed by solving the system

$$y_n = f(nh) + \sqrt{h} \sum_{j=0}^{2 \times \text{IORDER} - 2} \text{SW}(n+1, j+1) K(nh, jh) y_j, \quad n = 1, 2, \dots, 2 \times \text{IORDER} - 2.$$

- (c) Compute the inhomogeneous terms

$$\sigma_n = f(nh) + \sqrt{h} \sum_{j=0}^{2 \times \text{IORDER} - 2} \text{SW}(n+1, j+1) K(nh, jh) y_j, \quad n = 2 \times \text{IORDER} - 1, 2 \times \text{IORDER}, \dots, N.$$

- (d) Start the iteration for $n = 2 \times \text{IORDER} - 1, 2 \times \text{IORDER}, \dots, N$ to compute y_n from:

$$(1 - \sqrt{h} \text{WT}(1) K(nh, nh)) y_n = \sigma_n + \sqrt{h} \sum_{j=2 \times \text{IORDER} - 1}^{n-1} \text{WT}(n-j+1) K(nh, jh) y_j.$$

Note that for nonlinear weakly singular equations, the solution of a nonlinear algebraic system is required at step (b) and a single nonlinear equation at step (d).

9 Example

The following example generates the first 16 fractional convolution and 23 fractional starting weights generated by the fourth-order BDF method.

9.1 Program Text

Note: the listing of the example program presented below uses *bold italicised* terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
*      D05BYF Example Program Text
*      Mark 16 Release. NAG Copyright 1992.
*      .. Parameters ..
      INTEGER          NOUT
      PARAMETER       (NOUT=6)
      INTEGER          IORDER, IQ, ITPMT, ITIQ, LENFW, LDSW, LWK
      PARAMETER       (IORDER=4, IQ=3, ITPMT=2*IORDER-1, ITIQ=2*(IQ+1),
+                    LENFW=2*ITIQ, LDSW=ITIQ+ITPMT, LWK=4*ITIQ)
*      .. Local Scalars ..
      INTEGER          I, IFAIL, J
*      .. Local Arrays ..
      real            SW(LDSW,ITPMT), WORK(LWK), WT(LENFW)
*      .. External Subroutines ..
      EXTERNAL        D05BYF
```

```

*      .. Executable Statements ..
*
WRITE (NOUT,*) 'D05BYF Example Program Results'
WRITE (NOUT,*)
IFAIL = 0
*
CALL D05BYF(IORDER,IQ,LENFW,WT,SW,LDSW,WORK,LWK,IFAIL)
*
WRITE (NOUT,*) 'Fractional convolution weights'
WRITE (NOUT,*)
DO 20 I = 1, ITIQ
  WRITE (NOUT,99999) I - 1, WT(I)
20 CONTINUE
WRITE (NOUT,*)
WRITE (NOUT,*) 'Fractional starting weights'
WRITE (NOUT,*)
DO 40 I = 1, LDSW
  WRITE (NOUT,99999) I - 1, (SW(I,J),J=1,ITPMT)
40 CONTINUE
*
STOP
*
99999 FORMAT (1X,I5,7F9.4)
END

```

9.2 Program Data

None.

9.3 Program Results

D05BYF Example Program Results

Fractional convolution weights

0	0.6928
1	0.6651
2	0.4589
3	0.3175
4	0.2622
5	0.2451
6	0.2323
7	0.2164
8	0.2006
9	0.1878
10	0.1780
11	0.1700
12	0.1629
13	0.1566
14	0.1508
15	0.1457

Fractional starting weights

0	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
1	0.0565	2.8928	-6.7497	11.6491	-11.1355	5.5374	-1.1223
2	0.0371	1.7401	-2.8628	6.5207	-6.4058	3.2249	-0.6583
3	0.0300	1.3207	-2.4642	6.3612	-5.4478	2.7025	-0.5481
4	0.0258	1.1217	-2.2620	5.3683	-3.7553	2.2132	-0.4549
5	0.0230	0.9862	-2.0034	4.5005	-3.2772	2.7262	-0.4320
6	0.0208	0.9001	-1.8989	4.2847	-3.5881	2.8201	0.2253
7	0.0190	0.8506	-1.9250	4.4164	-4.0181	2.7932	0.1564
8	0.0173	0.8177	-1.9697	4.5348	-4.2425	2.7458	-0.0697
9	0.0160	0.7886	-1.9781	4.5318	-4.2769	2.6997	-0.2127
10	0.0149	0.7603	-1.9548	4.4545	-4.2332	2.6541	-0.2620
11	0.0140	0.7338	-1.9198	4.3619	-4.1782	2.6059	-0.2716
12	0.0132	0.7097	-1.8842	4.2754	-4.1246	2.5544	-0.2767
13	0.0125	0.6880	-1.8497	4.1933	-4.0662	2.5011	-0.2845
14	0.0119	0.6681	-1.8153	4.1109	-4.0004	2.4479	-0.2915
15	0.0114	0.6497	-1.7805	4.0279	-3.9304	2.3962	-0.2951

16	0.0110	0.6327	-1.7461	3.9463	-3.8598	2.3466	-0.2958
17	0.0105	0.6168	-1.7126	3.8677	-3.7907	2.2990	-0.2950
18	0.0102	0.6020	-1.6804	3.7926	-3.7238	2.2536	-0.2935
19	0.0098	0.5882	-1.6495	3.7209	-3.6589	2.2101	-0.2917
20	0.0095	0.5752	-1.6199	3.6523	-3.5961	2.1686	-0.2895
21	0.0093	0.5631	-1.5916	3.5867	-3.5356	2.1291	-0.2871
22	0.0090	0.5517	-1.5644	3.5240	-3.4774	2.0914	-0.2844
